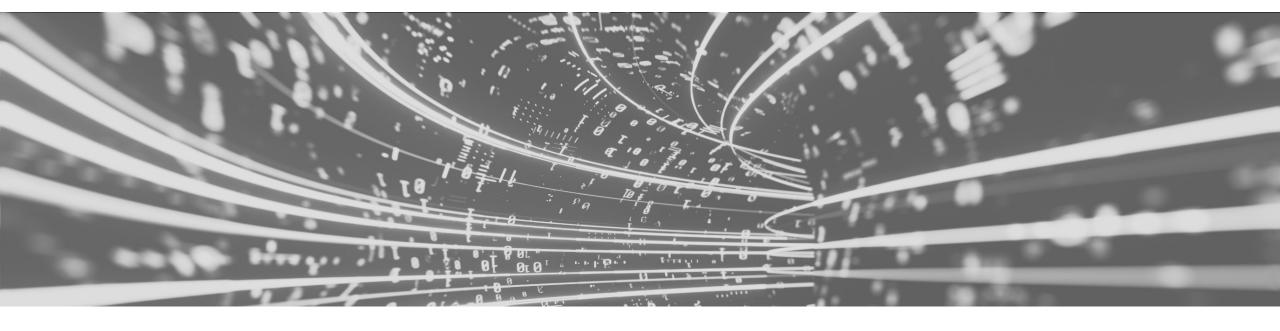
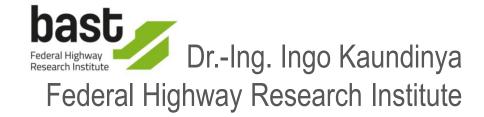
INTEGRATION OF TUNNEL SENSORS AND C2X TECHNOLOGY TO ENHANCE TUNNEL SAFETY IN GERMANY

RESEARCH PROJECT KITT





VI INTERNATIONAL TUNNELLING FORUM



AGENDA



- Background
- Utilization of C-ITS data
- KITT-Research Project: objective & functional principle
- Artificial Intelligence
- Training data set
- Visualization
- Demonstration
- Outlook

BACKGROUND



WHATS NEW?









Digitisation/ Mobility 4.0

C-ITS

Artificial Intelligence

Cyber Security

> How does this address and change the safety assessment in road tunnels?

UTILIZATION OF C-ITS DATA



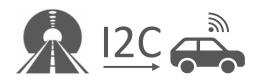
BASIC PRINCIPLES

- C-ITS Cooperative Intelligent Transport Systems
 - > Exchange of digital messages on traffic events and vehicle status between road users and the traffic infrastructure

C2X / V2X

- Car-2-Infrastructure (C2I) Communication
- Infrastructure-2-Car (I2C) Communication





UTILIZATION OF C-ITS DATA



IMPORTANT STANDARDIZED C-ITS MESSAGES

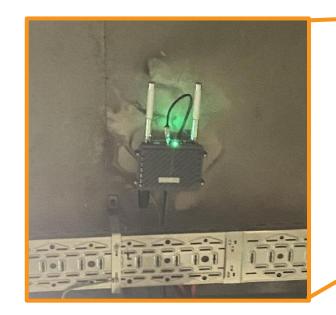
- CAM Cooperative Awareness Messages
 - continuous transmitted (~every second)
 - status of a vehicle: position, direction, speed or vehicle type
- DENM Decentralized Environmental Notification Messages
 - vent-based transmission
 - notifications of road users and infrastructure systems in case of safety-critical events with additional event information
- SPAT Signal Phase And Timing
- IVI In-Vehicle Information

UTILIZATION OF C-ITS DATA



REQUIRED EQUIPMENT

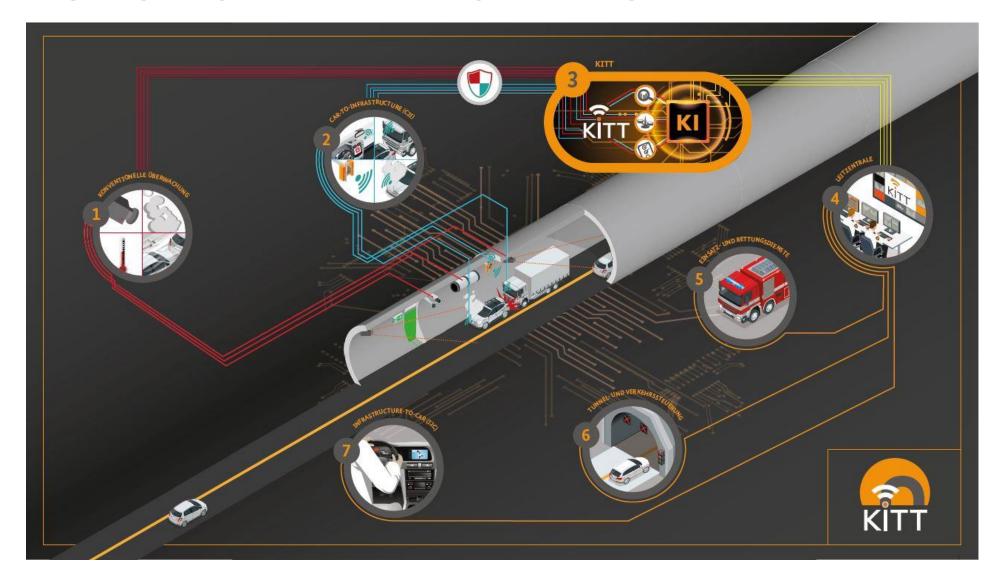
- OBU Onboard unit @ vehicle
- **RSU** Roadside Unit @ tunnel





FUNCTIONAL PRINCIPLE OF KITT

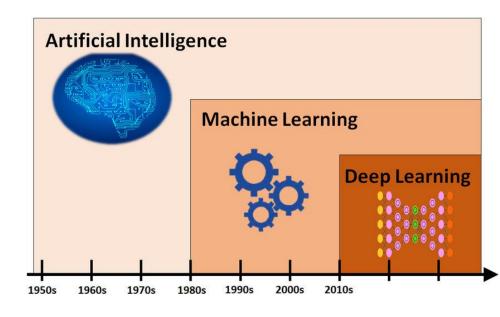






BASIC PRINCIPLES

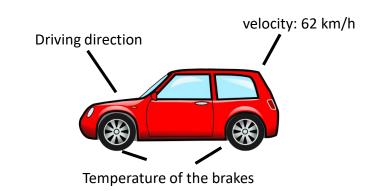
- Artificial Intelligence is used to explain that computers try to perform human activities
- Machine Learning can learn from experience to find patterns in a range of data
- "Weak Al":
 - y used for complex but recurring and precisely specified problems
 - has no creativity and no ability to learn independently
 - able to complete concrete tasks whose solutions she has previously learned

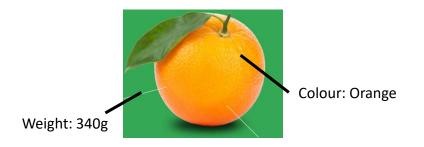




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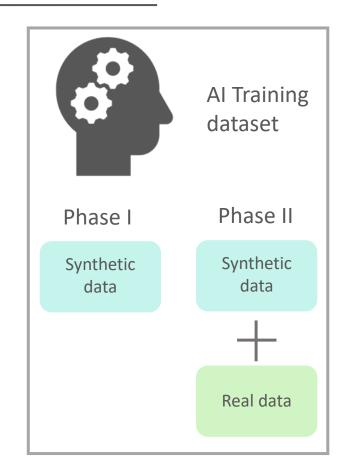


TRAINING CONCEPT

- Al module requires (large) training set with labelled variables and attributes
- Currently a very low rate of C-ITS capable vehicles on the road (<6%); however, numbers are increasing!
- Decision to set-up a training base using synthetic data
 - > SUMO: microscopic traffic simulation model
 - > ARTERY: C-ITS simulation framework



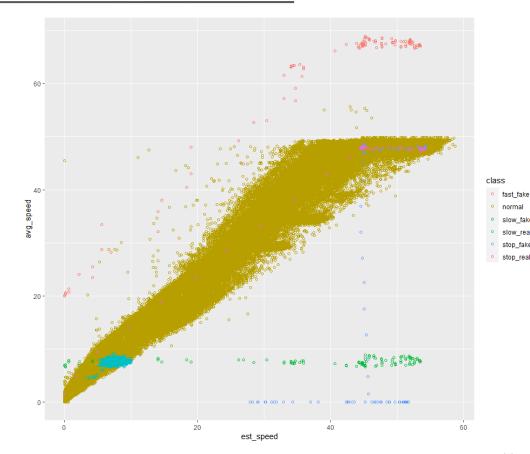






THE ROLE OF AI IN THE PROJECT

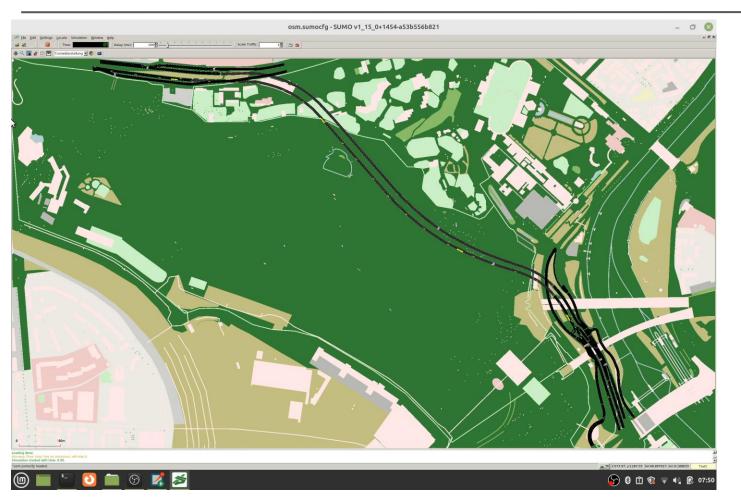
- Cope with the big amount of data transmitted by vehicles via C-ITS and sensor technology
- Detect anomalies in the data
 - > C-ITS-AI: improve the detection of (potential) critical traffic situations at an early stage
 - > Tunnel sensor-AI: additional analysis of tunnel sensor data
 - > IT-Security-AI: detect security-relevant events, e.g. Denial-of-Service, spoofing of C-ITS data
- Future: On-the-job learning learn from the reactions of the operators



TRAINING DATA SET



SUMO FOR TRAFFIC FLOW SIMULATION



- GUI for Simulation SUMO
- Yellow Vehicle normal Vehicle
- Red Vehicle eventvehicle (e.g. collision, wrong-way driver)

TRAINING DATA SET



EXAMPLE OF CAM OUTPUT VIA SIMULATION

```
ITS PDU Header:
Protocol Version: 2
Message ID: 2
Station ID: 2372
CoopAwarensess:
 Generation Delta Time: 10696
 Basic Container:
 Station Type: 5
 Reference Position:
  Longitude: 92089680
  Latitude: 488002490
  Semi Major Orientation: 3601
  Semi Major Confidence: 4095
   Semi Minor Confidence: 4095
  Altitude [Confidence]: 800001 [15]
High Frequency Container [Basic Vehicle]:
 Heading [Confidence]: 1623 [10]
 Speed [Confidence]: 825 [3]
 Drive Direction: 0
 Longitudinal Acceleration: 0
 Vehicle Length [Confidence Indication]: 1023 [0]
 Msg stats: 126 scheduled / 114811 existing / 485322 created
```

```
ITS PDU Header:
Protocol Version: 2
Message ID: 2
                                   type of the C-ITS message
Station ID: 4147
                                   ID of the vehicle
CoopAwarensess:
Generation Delta Time: 32624
Basic Container:
                                   type of the vehicle
 Station Type: 5
 Reference Position:
  Longitude: 92010090
                                   position of the vehicle
  Latitude: 488049440
  Semi Major Orientation: 3601
                                   orientation of the vehicle
  Semi Major Confidence: 4095
   Semi Minor Confidence: 4095
  Altitude [Confidence]: 800001 [15]
High Frequency Container [Basic Vehicle]:
 Heading [Confidence]: 1391 [10]
 Speed [Confidence]: 0 [3]
                                   speed of the vehicle
 Drive Direction: 0
 Longitudinal Acceleration: 0
 Vehicle Length [Confidence Indication]: 1023 [0]
 Msg stats: 160 scheduled / 970959 existing / 4070362 created
```

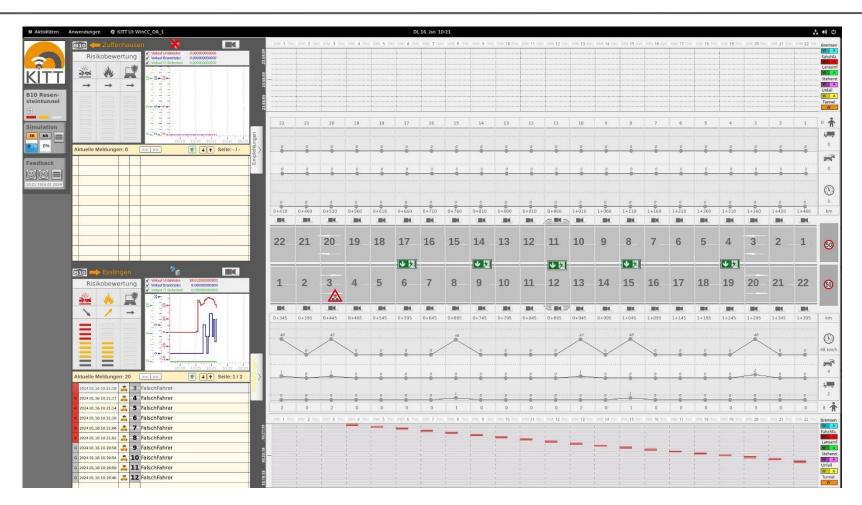
Vehicle before breakdown

Vehicle after breakdown

VISUALIZATION



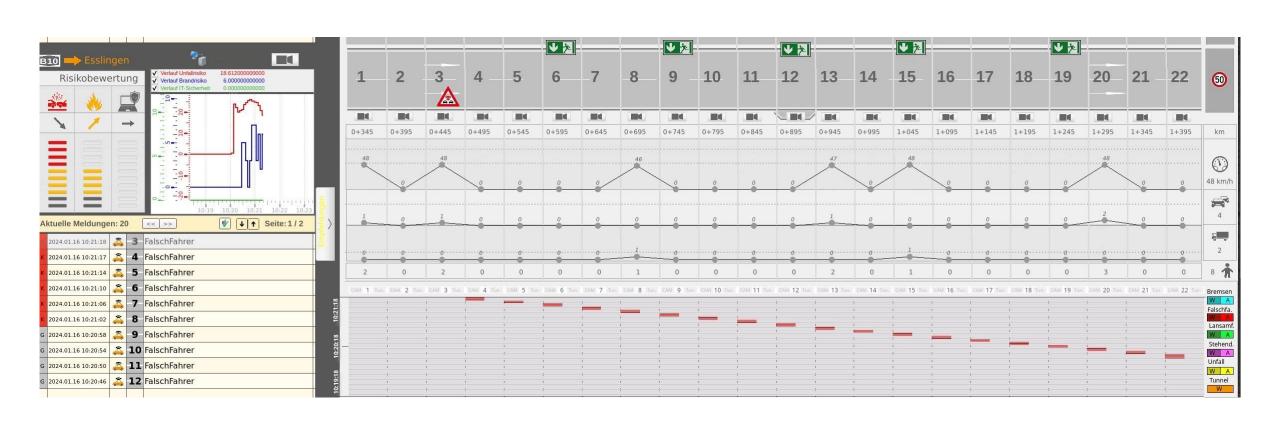
GRAPHICAL USER INTERFACE



VISUALIZATION



GRAPHICAL USER INTERFACE - DETAIL



DEMONSTRATION

Rosensteintunnel Stuttgart







- Lenght 1300 meter
- Twin-tube tunnel
- Opening: March 2022
- Costs: 456 Mio. €

DEMONSTRATION



ROSENSTEINTUNNEL

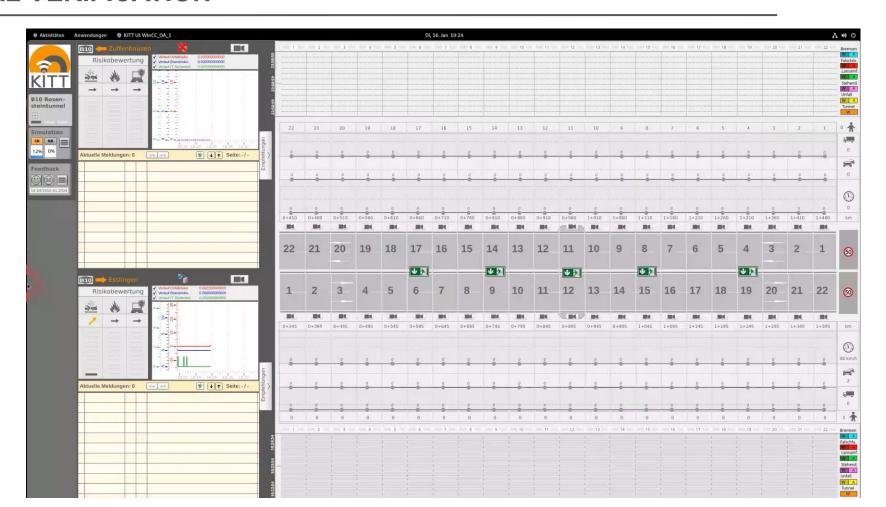
- Equipment of tunnel tube with 3 RSUs at both tunnel portals as well as in tunnel center
- Implementation of RSUs and other KITT modules into tunnel control and monitoring system
- Proof-of-concept planned with real-life test vehicles and also synthetic data for scenarios like "vehicle fire"
- Missing GNSS reception: functional verification mainly based on synthetic data
- Individual scenarios such as wrong-way drivers with vehicle VW ID.7



DEMONSTRATION



FUNCTIONAL VERIFICATION



CONCLUSION



LESSONS LEARNED, OUTLOOK

- Number of C-ITS vehicles at the moment is small, but steadily increasing. C-ITS data is already existing, but not (yet) used in tunnels.
- KITT showed great potential for C-ITS in tunnel safety
- For the future realization of autonomous driving on roads and highways it is necessary to ensure the functioning of C-ITS in tunnels
- Standardization & Harmonization



THANK YOU FOR YOUR ATTENTION!



Contact

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