

ZIPMANAGER Portable traffic management system

Martin Bambušek

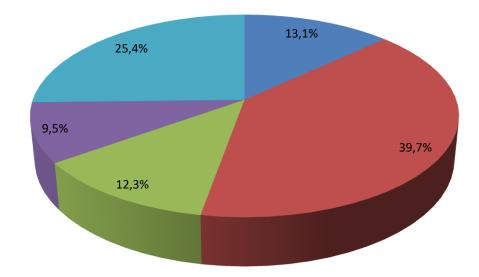
CAUSE OF CONGESTIONS ON HIGHWAYS





CAUSE OF CONGESTIONS ON HIGHWAYS

Long term workzone: 39,7% Short term workzone: 12,3% Accidents in workzones: 9,5% Accidents: 13,1% Other reasons: 25,4%





ZIPMANAGER SYSTEM

TRAFFIC RELATED ASPECTS

- DECREASE nr. of ACCIDENTS
- DECREASE TRAVEL TIMES
- INFORM DRIVERS and OPERATORS

TECHNICAL ASPECTS:

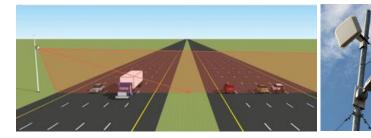
- PORTABLE, EASY TO INSTALL TELEMATIC SYSTEM
- USER DEFINED FUNCTIONS AND ALGORITHMS
- CONSIST OF HIGH VISIBILITY TRAFFIC LED SIGNS
- INDEPENDENT POWER SUPPLY
- DYNAMIC DATA-DRIVEN REMOTE CONTROL FROM SERVER APPLICATION
- USING BIG DATA FCD FOR WORKZONE TRAFFIC FLOW MONITORING











COMMUNICATION







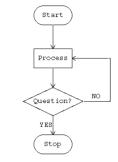






EVALUATION





12	A1B1	A1B2	A1B3	A2B1	A2B2	A2B3	A3B1	A3B2	A3B3
C1D1	К	k	k	k	k	k	K, PB	k	K, PC
C1D2	K	k	k	k	k	k	K, PB	k	K, PC
C1D3	К	k	k	k	k	k	K, PB	k	K, PC
C2D1	k	k	k	k	k	k	K, PB	k	k
C2D2	Р	Р	Р	р	n	n	P, PB	r	r
C2D3	Р	Р	Р	р	n	n	P, PB	r	r
C3D1	k	k	k	k	k	k	K, PB	k	K, PD
C3D2	P	Р	Р		n	n	P, PB		r
C3D3	Р	Р	Р	р	n	n	P, PB	r	r

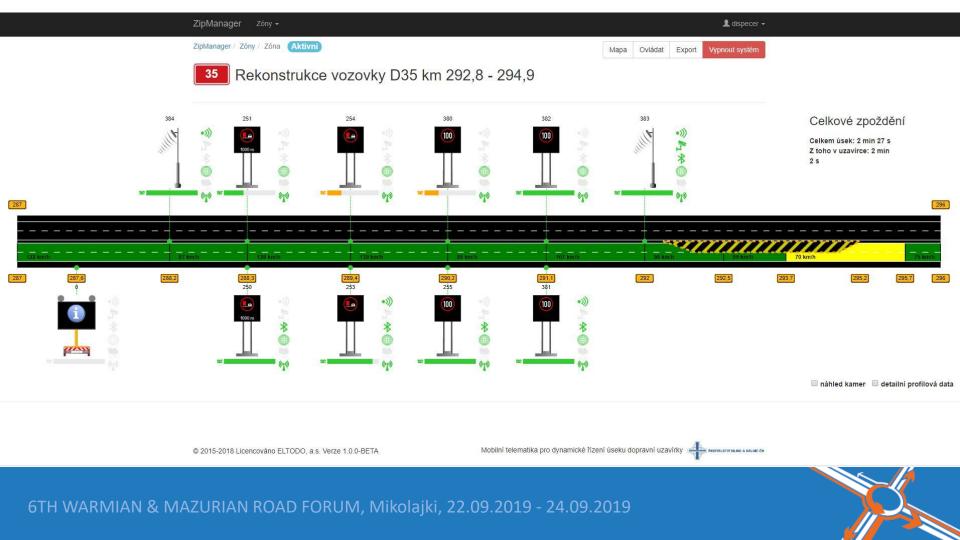




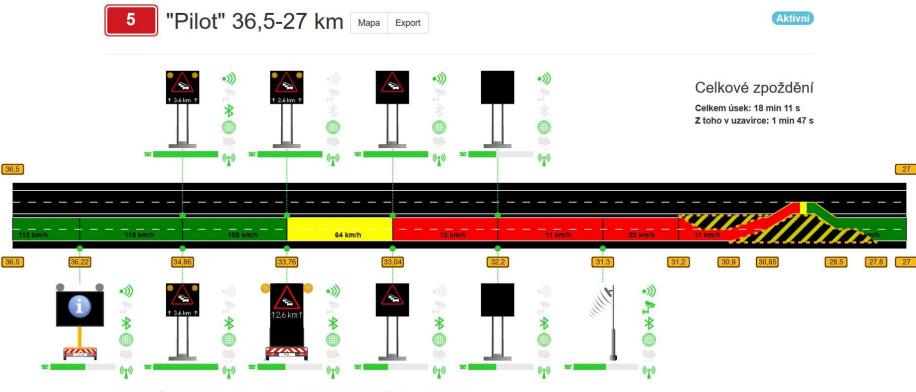
POWER SUPPLY











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Řez Detekce, stanice P	💥 🕺 Řez D	etekce, stani	ce P			Řez Profil_1, stanice P
Status Průběh Kamera	Status	Průběh				Status Prùbéh Osta
	_	A A A A A A A A A A A A A A A A A A A	vý JP —— In	15.48.0	Kabad	Rychlost: Intenzita: Baterie: GPS: Rychlost pravý JP: Intenzita pravý JP: Rychlost levý JP: Intenzita levý JP: Intenzita protisměr levý JP: Rychlost protisměr levý JP: Rychlost protisměr pravý JP: Intenzita protisměr pravý
	Čas	Rychlost pravý JP	Intenzita pravý JP	Rychlost levý JP	Intenzita levý JP	JP:
	15:07:02	87,84	19	88,117	0	
	15:08:02	74,859	32	82,898	2	
	15:09:02	82,207	22	89,047	1	
	15:10:02	85,555	19	89,047	o	
	15:11:02	92,582	18	89,047	0	
	15:12:02	92,863	14	85,41	1	
	15:13:02	92,52	15	72,34	1	
	15:14:02	86,875	24	96,398	1	
	15:15:02	80,801	19	96,398	0	
	15:16:02	97,914	22	115,516	4	

 ost:
 99 km/h

 cita:
 17

 ie:
 12,3 V

 49,85660325,
 13,8759229333333

 iost pravý JP:
 84 km/h

 izita pravý JP:
 8

 iost levý JP:
 114 km/h

 izita protisměr levý JP:
 126 km/h

 izita protisměr levý JP:
 10

 iost protisměr pravý
 101 km/h



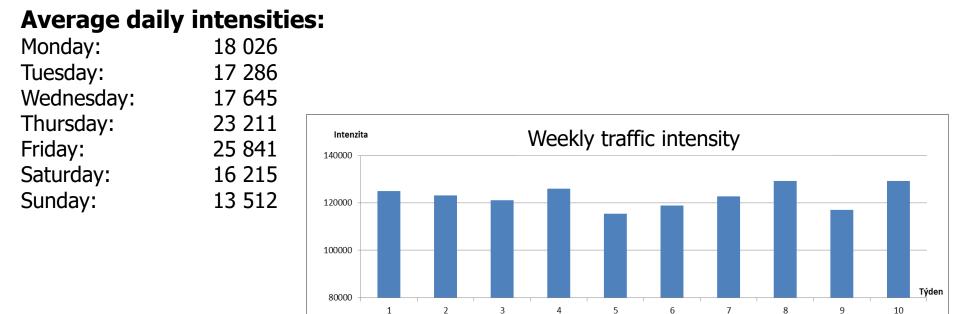






TRAFFIC INTENSITY

In all phases the traffic intensity was comparable



PILOT TEST EVALUATION – congestion time

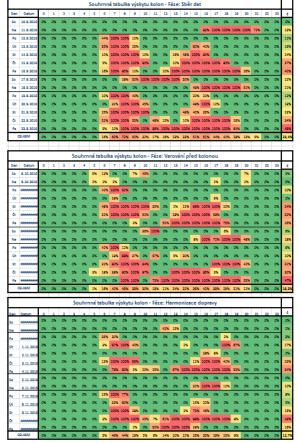
Congestions in a days of week						
Phase	Data collection	Congestion warning	Harmonization			
Mon	11,5%	8,0%	5,5%			
Tue	17,0%	6,0%	11,0%			
Wed	23,5%	32,5%	8,5%			
Thu	35,0%	31,0%	33,0%			
Fri	44,0%	37,0%	25,0%			
Sat	11,0%	4,5%	0,0%			
Sun	22,0%	9,0%	6,0%			
Total	23,4%	18,3%	12,7%			



Phase 1 **"DATA COLECTION"** 23% time of congestion

Phase 2 "CONGESTION WARNING" 18% time of congestion

Phase 3 **"TRAFFIC FLOW HARMONIZATION"** 12% time of congestion





CONCLUSIONS

- System has big potential for decreasing of external loses from congestion in workzones and increasing the traffic safety
- Dynamic mobility model and the control algorithms is ready to be tested and integrated into the dynamic Use case for C-ITS
- The modularity of system is ready for any workzones layout, even the short-term Workzones
- System is ready to **integrate any other ITS equipment** (detectors, portable traffic Lights, standard trailers etc.)
- From the technical point of view system has been modified and been proved as reliable and it is ready to use in commercial applications
- System has very positive CBA index (investment of 0,5-1,5% of the total budget for reconstructed part of highway)





Thank you for your attention

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